

We begin with some very basic linear algebra.
The models and signals in this course
will be associated with vector spaces and
operations on them.

1 Given a field F of scalars, here F will
be either \mathbb{C} the set of complex numbers, or \mathbb{R}
the set of real numbers, a vector space
 V over F is a non-empty set with elements
called vectors and two rules of combination
vector addition and scalar multiplication, respectively
denoted

$$+ : V \times V \rightarrow V$$

$$(v, w) \mapsto v + w$$

and $\cdot : F \times V \rightarrow V$

$$(a, v) \mapsto a \cdot v \text{ or simply } av$$

obeying the axioms.

- (i) $v + w = w + v$
- (ii) $(v + w) + z = v + (w + z)$
- (iii) there exists $0 \in V$ such that $0 + v = v \quad \forall v \in V$
- (iv) for each $v \in V$ there exists $(-v) \in V$ such that
 $v + (-v) = 0$
- (v) $a(bv) = (ab)v$ where $a, b \in F, v \in V$
- (vi) $a(v + w) = av + aw$ $a \in F, v, w \in V$

$$(vii) \quad (a+b)v = av + bv \quad a, b \in F, v \in V$$

$$(viii) \quad 1 \cdot v = v \quad 1 \in F$$

Examples $V = \mathbb{R}^n = \{(v_1, v_2, \dots, v_n) : v_i \in \mathbb{R}\}$

$$V = \text{Polynomials of degree } \leq k \text{ with complex coefficients}$$

$$V = \text{set of all continuous functions from interval } [0, 1] \text{ to } \mathbb{R}.$$

2 A mapping $L: V \rightarrow W$ from vector space V to vector space W over the same field F is said to be linear if

$$L(av + b\tilde{v}) = aL(v) + bL(\tilde{v})$$

for all $a, b \in F$ and $v, \tilde{v} \in V$

Example $V = \text{Set of all polynomials of degree } \leq k \text{ in indeterminate } \lambda \text{ and complex coefficients.}$

$$W = V$$

$$L: V \rightarrow W \text{ defined as } L = \frac{d}{d\lambda}$$

Observe that the linear mappings, all taken together form a vector space $\mathcal{L}(V, W)$.

over the same field F .

hint: $L_1 + L_2$ is defined by

$$(L_1 + L_2)(v) = L_1(v) + L_2(v)$$

a L is defined by

$$(aL)(v) = aL(v)$$

3. An indexed set of vectors $\{v_1, v_2, \dots, v_k\}$ in a vector space V , is said to be linearly independent if

$$\sum_{i=1}^k \alpha_i v_i = 0 \quad \Rightarrow \quad \alpha_i = 0 \quad \forall i=1, 2, \dots, k$$

Suppose V has the property that there is at least one indexed subset $\{v_1, v_2, \dots, v_k\} \subset V$ which is linearly independent and any other subset of cardinality $> k$ is not linearly independent. We then say that V is a vector space of dimension k , and call such a linearly independent set $\{v_1, v_2, \dots, v_k\}$ a basis for V .

4. If V is of dimension k and $S_k = \{v_1, v_2, \dots, v_k\}$ is a basis for V , then any vector $v \in V$ can be expressed as a linear combination of the basis vectors given.

proof: $S = \{v_1, v_2, v_3, \dots, v_k, v\}$ is not

linearly independent since $\text{Cardinality}(S) = k+1$.

Hence there exist constants α_i , not all zero such that

$$\sum_{i=1}^k \alpha_i v_i + \alpha_{k+1} v = 0$$

$\alpha_{k+1} \neq 0$ since S_k is a basis by hypothesis.

Hence

$$v = \sum_{i=1}^k \left(-\frac{\alpha_i}{\alpha_{k+1}} \right) v_i \quad \square$$

A basis representation of the form

$$v = \sum_{i=1}^k \beta_i v_i$$

is unique, for a fixed basis. We have thus a one-to-one correspondence

$$v \leftrightarrow (\beta_1, \beta_2, \dots, \beta_k) \in F^k$$

called coordinate representation.

In the previous paragraph we have associated a simple ordered tuple (list) of numbers, $(\beta_1, \beta_2, \dots, \beta_k)$ uniquely with $v \in V$. We can be a bit more choosy. We could decide to write this list as a column matrix

$$\begin{pmatrix} \beta_1 \\ \vdots \\ \beta_k \end{pmatrix} \quad \text{or} \quad \text{as a row matrix } (\beta_1 \ \beta_2 \ \dots \ \beta_k).$$

Suppose we go with column representation. Then each vector v is associated uniquely with its coordinate column matrix

$$\begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{pmatrix} \in \mathbb{R}^k \text{ or } \mathbb{C}^k$$

This choice will govern how we proceed in (6) below.

5. Matrix representation of a linear map.

Let $A \in \mathcal{L}(V, W)$. Let

$S_V = \{v_1, v_2, \dots, v_n\}$ and $S_W = \{w_1, w_2, \dots, w_m\}$ be bases for V and W respectively.

With these fixed bases, we represent

$$A v_j = \sum_{i=1}^m a_{ij} w_i \quad j=1, 2, \dots, n.$$

The $m \times n$ matrix

$$\tilde{A} = [a_{ij}]$$

represents A in the chosen bases.

6. Change of coordinates under a change of basis.

Given two distinct bases

$S = \{v_1, v_2, \dots, v_k\}$ and $S' = \{v'_1, v'_2, \dots, v'_k\}$
for V , let us denote

$$v'_j = \sum_{i=1}^k t_{ij} v_i$$

(*) Thus the columns of the matrix

$$T = [t_{ij}]$$

are the coordinate representations of the new basis vectors in S' in terms of the old basis vectors in S .

Suppose the new coordinates of a general vector $v \in V$ are given by the ordered list $(\beta'_1, \beta'_2, \dots, \beta'_k)$ viewed as a column matrix.

Then,

$$\begin{aligned}v &= \sum_{j=1}^k \beta'_j v'_j \\&= \sum_{j=1}^k \beta'_j \sum_{i=1}^k t_{ij} v_i \\&= \sum_{i=1}^k \left(\sum_{j=1}^k t_{ij} \beta'_j \right) v_i \\&= \sum_{i=1}^k \beta_i v_i\end{aligned}$$

where $\beta_i = \sum_{j=1}^k t_{ij} \beta'_j$ indicates that

(**) the rows of T are used to express the old coordinates β_i in terms of the new coordinates β'_j .

Remark

Compare (*) and (**). We can say (**) succinctly as

$$\beta = T \beta'$$

or diagrammatically,

$$\beta \xrightarrow{T} \beta'$$

$$S \xrightarrow{T} S' \quad (\text{transforming sets})$$

$$\beta \xleftarrow{T} \beta' \quad (\text{transforming coordinates})$$

The matrix T is necessarily invertible. Prove this.

7. Suppose $A \in \mathcal{L}(V, W)$ and $\dim(V) = m$, $\dim(W) = m$. Let $\tilde{A} = [a_{ij}]$ denote the $m \times m$ matrix representation of A with respect to bases $S_V \subset V$ and $S_W \subset W$. If,

$$w = Av$$

and β_v and β_w represent the coordinates (as columns) of v and w respectively. Then

$$\beta_w = \tilde{A} \beta_v \quad \left. \begin{array}{l} \text{(matrix-vector)} \\ \text{(multiplication)} \end{array} \right\}$$

Verify this. It justifies the column representation chosen in (4) above.

8. Change of matrix representation under change of basis.

Let V and W be vector spaces of dimension n and m respectively. Let $A \in \mathcal{L}(V, W)$. In a basis S_V for V and S_W for W , this map has a matrix representation $\tilde{A} = [a_{ij}]$

with m rows and n columns. Suppose the bases undergo transformations to new bases

$$S_V \xrightarrow{T_V} S'_V$$

and

$$S_W \xrightarrow{T_W} S'_W$$

where T_V and T_W are $n \times n$ and $m \times m$ invertible matrices, respectively.

Observe that for any vector $v \in V$ with image $w = Av \in W$, the coordinate vectors are given in the original bases by

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$$(+) \quad \beta_w = \tilde{A} \beta_v$$

From (6) we note that the coordinate vectors β_w' and β_v' in the new bases, are related to the coordinate vectors in the old bases by

$$\beta_v = T_v \beta_v'$$

$$\beta_w = T_w \beta_w'$$

Substitution in the formula (+), we get

$$T_w \beta_w' = \tilde{A} T_v \beta_v'$$

or equivalently

$$\begin{aligned} \beta_w' &= T_w^{-1} \tilde{A} T_v \beta_v' \\ &= \tilde{A}' \beta_v' \end{aligned}$$

where, $\tilde{A}' = T_w^{-1} \tilde{A} T_v$
is the matrix representation of A

in the new bases.

9. Change of matrix representation of a linear self-map

$$A: V \rightarrow W = V$$

Since W and V are same, there is only one basis to change, and only one matrix defining basis change, namely

$$T_W = T_V = P \quad \text{say.}$$

Then,

$$\tilde{A}' = P^{-1} \tilde{A} P$$

a similarity transformation of the matrix A .

Remark

We care about what aspects of a linear map representation are invariant to (arbitrary) changes of bases.